

STOKES' THEOREM

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$$\begin{aligned}
 \int_{\partial\Sigma} (P dx + Q dy + R dz) &= \iint_{\Sigma} \left(dP \wedge dx + dQ \wedge dy + dR \wedge dz \right) \\
 &= \iint_{\Sigma} \left[\left(\frac{\partial P}{\partial x} dx + \frac{\partial P}{\partial y} dy + \frac{\partial P}{\partial z} dz \right) \wedge dx + \left(\frac{\partial Q}{\partial x} dx + \frac{\partial Q}{\partial y} dy + \frac{\partial Q}{\partial z} dz \right) \wedge dy + \left(\frac{\partial R}{\partial x} dx + \frac{\partial R}{\partial y} dy + \frac{\partial R}{\partial z} dz \right) \wedge dz \right] \\
 &= \iint_{\Sigma} \left[\left(0 - \frac{\partial P}{\partial y} dx \wedge dy + \frac{\partial P}{\partial z} dz \wedge dx \right) + \left(\frac{\partial Q}{\partial x} dx \wedge dy + 0 - \frac{\partial Q}{\partial z} dy \wedge dz \right) + \left(-\frac{\partial R}{\partial x} dz \wedge dx + \frac{\partial R}{\partial y} dy \wedge dz + 0 \right) \right] \\
 &= \iint_{\Sigma} \left[\left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx \wedge dy + \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) dy \wedge dz + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) dz \wedge dx \right]
 \end{aligned}$$

Abbreviations

- One can use a single vector symbol, such as \vec{F} , to denote $\langle P, Q, R \rangle$.
- Likewise, $d\vec{r}$ is often used to represent $\langle dx, dy, dz \rangle$. If one wishes to emphasize the magnitude and direction of $d\vec{r}$, then one factors it as $\vec{T} ds$ where \vec{T} is the unit tangent vector and ds is the arc length differential $\sqrt{dx^2 + dy^2 + dz^2}$.
- The vector $\langle dy \wedge dz, dz \wedge dx, dx \wedge dy \rangle$ may be factored as $\vec{n} d\sigma$ where \vec{n} the outward unit normal vector and $d\sigma$ is the surface area differential $\sqrt{(dy \wedge dz)^2 + (dz \wedge dx)^2 + (dx \wedge dy)^2}$.
- The vector $\left\langle \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}, \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}, \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right\rangle$ is often abbreviated as $\vec{\nabla} \times \langle P, Q, R \rangle$ or $\text{curl} \langle P, Q, R \rangle$.
- Thus, Stokes' Theorem can be succinctly written as $\int_{\partial\Sigma} \vec{F} \cdot \vec{T} ds = \iint_{\Sigma} (\vec{\nabla} \times \vec{F}) \cdot \vec{n} d\sigma$.
- To be even more succinct, write ω for $P dx + Q dy + R dz$ and $d\omega$ for $dP \wedge dx + dQ \wedge dy + dR \wedge dz$, producing $\int_{\partial\Sigma} \omega = \iint_{\Sigma} d\omega$.

Assumptions

- Σ is assumed to be an oriented surface and $\partial\Sigma$ to be the positively oriented boundary of Σ .
- The unit outward normal vector \vec{n} and is assumed to be continuous on Σ .
- The unit tangent vector \vec{T} and is assumed to be continuous on $\partial\Sigma$.
- $\langle P, Q, R \rangle$ and its first partial derivatives are assumed to be continuous in an open region containing Σ and $\partial\Sigma$.